

Robotics Systems Types - Feature #2326

Deploy Sources/Javadoc

06/16/2015 04:12 PM - P. Holthaus

Status:	Rejected	Start date:	06/16/2015
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	0%
Category:	java	Estimated time:	0.00 hour
Target version:	rsb-0.12		

Description

Would it make sense to deploy javadoc and sources for rst? One could for example alter pom.xml like this:

```
<build>
<plugins>
<plugin>
<groupId>org.apache.maven.plugins</groupId>
<artifactId>maven-source-plugin</artifactId>
<version>2.4</version>
<executions>
<execution>
<id>attach-sources</id>
<goals>
<goal>jar</goal>
</goals>
</execution>
</executions>
</plugin>
<plugin>
<groupId>org.apache.maven.plugins</groupId>
<artifactId>maven-javadoc-plugin</artifactId>
<version>2.10.3</version>
<executions>
<execution>
<id>attach-javadocs</id>
<goals>
<goal>jar</goal>
</goals>
</execution>
</executions>
</plugin>
</plugins>
</build>
```

History

#1 - 06/16/2015 05:38 PM - J. Wienke

- Status changed from New to Rejected

Since everything is generated code, without nice docs, there is nothing to learn from that.

