Robotics Systems Types - Feature #2382
new converter JointAccelerations

09/02/2015 06:39 PM - N. Dehio

Status:	Resolved		**Start date:**	09/02/2015
Priority:	High		**Due date:**	
Assignee:			**% Done:**	100%
Category:			**Estimated time:**	0.00 hour
Target version:				

Description

Please commit my new (tested) converter JointAccelerations.

Attached you can find my git patch.

As a requirement, the rci issue "new RCI JointAccelerations" and rst issue "new rst proto JointAccelerations" have to be solved!

Related issues:

Blocked by Robot Control Interface - Feature # 2380: new RCI JointAccelerations	**Resolved**	**09/02/2015**

History

#1 - 09/03/2015 04:26 PM - J. Wienke

- Blocked by Feature #2380: new RCI JointAccelerations added

#2 - 09/22/2015 04:24 PM - D. Wigand

- Status changed from New to Resolved

- % Done changed from 70 to 100

https://code.cor-lab.org/projects/rst/repository/rst-converters/revisions/395e8a8ef5990dd9e629eccd3c35fb87985d8ffa

Files

0001-Added-JointAccelerationsConverter.patch	8.59 KB	09/02/2015	N. Dehio