

Robotics Systems Types - Feature #2382

new converter JointAccelerations

09/02/2015 06:39 PM - N. Dehio

Status:	Resolved	Start date:	09/02/2015
Priority:	High	Due date:	
Assignee:		% Done:	100%
Category:		Estimated time:	0.00 hour
Target version:			
Description			
Please commit my new (tested) converter JointAccelerations. Attached you can find my git patch. As a requirement, the rci issue "new RCI JointAccelerations" and rst issue "new rst proto JointAccelerations" have to be solved!			
Related issues:			
Blocked by Robot Control Interface - Feature # 2380: new RCI JointAccelerations		Resolved	09/02/2015

History

#1 - 09/03/2015 04:26 PM - J. Wienke

- Blocked by Feature #2380: new RCI JointAccelerations added

#2 - 09/22/2015 04:24 PM - D. Wigand

- Status changed from New to Resolved

- % Done changed from 70 to 100

<https://code.cor-lab.org/projects/rst/repository/rst-converters/visions/395e8a8ef5990dd9e629eccd3c35fb87985d8ffa>

Files

0001-Added-JointAccelerationsConverter.patch	8.59 KB	09/02/2015	N. Dehio
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