

RSB Depth Sensor Support - Feature #2389

Feature # 2388 (New): Initial version of Kinect 2 SDK Plugin

Color/Depth/Infrared and Skeleton Grabbing

09/16/2015 10:09 PM - M. Goerlich

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|------------------------|---------------------|------------------------|------------|
| Status: | New | Start date: | 09/16/2015 |
| Priority: | Normal | Due date: | |
| Assignee: | | % Done: | 70% |
| Category: | Kinect SDK 2 Plugin | Estimated time: | 0.00 hour |
| Target version: | | | |
| Description | | | |

History

#1 - 09/16/2015 10:26 PM - M. Goerlich

- % Done changed from 0 to 70

The Streams can be grabbed and published through the configurable grabber. Since currently the Kinect 2 SDK does not offer any configuration of streams a videomode option has been implemented through OpenCV, but it performs badly (probably because the debug library is being used? needs to be tested).

A longer test within the apartment context yielded a Framerate of around 28-31 FPS for depth + skeleton grabbing and 22-25 FPS for grabbing depth + skeleton + 720p color images. Scaling the images seems to limit the performance since it happens in the grabbing thread and converting + sending is done in separate threads, but still all streams run at the same frame rate.

The depth image seems a bit dark but it is unclear at the moment what unit the pixel values are in.