

RSB Depth Sensor Support - Feature #2396

Feature # 2388 (New): Initial version of Kinect 2 SDK Plugin

Point Cloud Grabbing

09/16/2015 10:44 PM - M. Goerlich

Status:	New	Start date:	09/16/2015
Priority:	Normal	Due date:	
Assignee:		% Done:	0%
Category:	Extension2	Estimated time:	0.00 hour
Target version:			
Description			
A rst.geometry.PointCloud3DFloat and a rst.vision.AugmentedPointCloud3DFloat could created by the SDKs (since sdks usually offer specific methods to map coordinates which can involve camera parameters).			