

Robotics Service Bus - Tasks #240

Refactor C++ Implementation to 2011-04-13 Domain Model

04/13/2011 05:55 PM - J. Moringen

Status:	Resolved	Start date:	03/02/2011
Priority:	Normal	Due date:	
Assignee:	S. Wrede	% Done:	100%
Category:	C++	Estimated time:	20.50 hours
Target version:			
Description			
Subtasks:			
Tasks # 239: Convert RSBFactory to Singleton			Resolved
Tasks # 241: Renaming of core classes			Resolved
Tasks # 242: namespace modifications			Resolved
Tasks # 243: Improved converter selection			Resolved
Tasks # 244: Adapt Subscription and Handler			Resolved
Tasks # 245: Introduce Participant base class			Resolved
Tasks # 254: Separation of in and out routes in eventprocessing			Resolved
Tasks # 255: Separate In and OutConnectors			Resolved
Tasks # 256: Move scope to Participant class			Resolved
Tasks # 257: Remove Subscription			Resolved
Tasks # 258: Integrate Service idea			Resolved
Tasks # 259: Create Scope class			Resolved
Tasks # 260: Unified handling ParticipantConfiguration			Resolved
Tasks # 261: Dynamic connector creation			Resolved
Tasks # 223: Model implementation of Methods according to the domain model			Resolved

History

#1 - 05/13/2011 06:39 PM - J. Wienke

- Status changed from New to Resolved