

Robot Control Interface - Feature #2444

Update for RCI types JointVelocities and JointAccelerations

11/25/2015 11:39 AM - N. Dehio

Status:	Resolved	Start date:	11/25/2015
Priority:	High	Due date:	
Assignee:	D. Wigand	% Done:	100%
Category:	Software	Estimated time:	0.00 hour
Target version:			
Description			
<p>Please commit my updated (tested) RCI types. I adapted JointVelocities and JointAccelerations according to JointAngles to provide functions like setFromRad_s(). Additionally I updated the JointVelocitiesTest and created a similar JointAccelerationsTest. Attached you can find my svn patch.</p>			

Associated revisions

Revision 736 - 12/11/2015 11:47 AM - D. Wigand

Update for RCI types JointVelocities and JointAccelerations. Closes #2444

History

#1 - 12/11/2015 11:50 AM - D. Wigand

- Status changed from New to Resolved
- % Done changed from 80 to 100

Applied in changeset r736.

Files

UpdateJointVelocitiesAndJointAccelerations.diff	33.4 KB	11/25/2015	N. Dehio
---	---------	------------	----------