CoR-Lab Tutorials - Tasks #2454
Sensor fusion tutorial: make a distribution

12/08/2015 11:21 AM - J. Moringen

Status:	Resolved		**Start date:**	12/09/2015
Priority:	Normal		**Due date:**	
Assignee:	J. Moringen		**% Done:**	100%
Category:			**Estimated time:**	0.00 hour
Target version:	Schulung			

Description

Maybe use toolkit distribution as a starting point. Important:

- ICL with OpenGL support
- RCT (C++)

Subtasks:

Tasks # 2470: Sensor fusion tutorial: Remove rct-tools from distribution	**Resolved**

History

#1 - 12/08/2015 11:24 AM - J. Moringen

- Description updated

#2 - 12/08/2015 12:18 PM - J. Moringen

- Status changed from New to In Progress

#3 - 12/08/2015 01:22 PM - J. Moringen

- % Done changed from 0 to 50

Question: which, if any, ROS components are needed by rct-cpp?

#4 - 12/09/2015 10:40 AM - J. Moringen

- % Done changed from 50 to 80

#5 - 12/10/2015 09:19 AM - J. Moringen

- Status changed from In Progress to Resolved