

CoR-Lab Tutorials - Tasks #2461

Sensor fusion tutorial: create "sensor fusion" component

12/08/2015 11:33 AM - J. Moringen

Status:	Resolved	Start date:	12/08/2015
Priority:	Normal	Due date:	
Assignee:	M. Goerlich	% Done:	100%
Category:		Estimated time:	0.00 hour
Target version:	Schulung		

Description

- CMake-based
- Receive tracking results from both sensors
- Obtain Coordinate systems
- Transform tracking results
- Publish transformed results for visualization

History

#1 - 12/09/2015 05:49 PM - M. Goerlich

- Status changed from New to Resolved

- % Done changed from 0 to 100

See source: [sensor-fusion-with-rsb|kinect-merging/src/fuse.cpp](#)