

## CoR-Lab Tutorials - Tasks #2462

### Sensor fusion tutorial: create transform provider component

12/08/2015 11:34 AM - J. Moringen

<b>Status:</b>	Resolved	<b>Start date:</b>	12/08/2015
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	M. Goerlich	<b>% Done:</b>	100%
<b>Category:</b>		<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	Schulung		
<b>Description</b>			
<ul style="list-style-type: none"><li>- RCT-based</li><li>- Obtain transforms using calibration tool or via fiddling</li></ul>			

#### History

#1 - 12/09/2015 05:22 PM - M. Goerlich

- Status changed from New to Resolved

- % Done changed from 0 to 100

See <https://code.cor-lab.de/projects/skeleton-merging/repository/revisions/master/entry/tools/rct-transform-receiver.cpp> .