Robotics Service Bus - Feature #2512

Feature # 2509 (Resolved): Cause filter

Cause filter [Python]

03/08/2016 01:24 PM - J. Moringen

Status:	Resolved	**Start date:**	03/08/2016
Priority:	Normal	**Due date:**	
Assignee:	J. Moringen	**% Done:**	100%
Category:	Python	**Estimated time:**	0.00 hour
Target version:	rsb-0.15		

Description

Associated revisions

Revision eb4cb13b - 06/16/2016 11:53 AM - J. Moringen

Added CauseFilter class in rsb/filter.py

fixes #2512

- rsb/filter.py (CauseFilter): new class; filters events based on their cause vectors
- test/filter_test.py (CauseFilterTest): new class; test suite for CauseFilter class

History

#1 - 06/08/2016 09:01 PM - J. Moringen

- Target version changed from rsb-0.14 to rsb-0.15

#2 - 06/15/2016 06:41 PM - J. Moringen

- Status changed from New to In Progress

- Assignee set to J. Moringen

- % Done changed from 0 to 50

#3 - 06/16/2016 12:00 PM - J. Moringen

- Status changed from In Progress to Resolved

- % Done changed from 50 to 100

Applied in changeset commit:rsb-python|eb4cb13bfe781419ccea9a913fcade8a5ef11486.