Robotics Service Bus - Tasks #256

Tasks # 240 (Resolved): Refactor C++ Implementation to 2011-04-13 Domain Model

Move scope to Participant class

04/27/2011 04:43 PM - J. Wienke

Status:ResolvedStart date:04/27/2011Priority:NormalDue date:

Assignee: J. Wienke % Done: 100%
Category: C++ Estimated time: 1.00 hour

Target version:

Description

Every participant has one scope, make this clear.

- Maintain scope ONLY in Participant.
- Remove uri from Listener

Related issues:

Related to Robotics Service Bus - Tasks # 259: Create Scope class Resolved 04/27/2011

Associated revisions

Revision 5411bc3d - 04/29/2011 12:31 PM - J. Wienke

remove duplicated scope from listener and informer and move it to participant

fixes #256

History

#1 - 04/29/2011 12:20 PM - J. Wienke

- Status changed from New to In Progress

#2 - 04/29/2011 12:31 PM - J. Wienke

- % Done changed from 0 to 100

#3 - 04/29/2011 01:10 PM - J. Wienke

- Status changed from In Progress to Resolved
- Assignee changed from S. Wrede to J. Wienke

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