

Robotics Service Bus - Tasks #256

Tasks # 240 (Resolved): Refactor C++ Implementation to 2011-04-13 Domain Model

Move scope to Participant class

04/27/2011 04:43 PM - J. Wienke

<b>Status:</b>	Resolved	<b>Start date:</b>	04/27/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Wienke	<b>% Done:</b>	100%
<b>Category:</b>	C++	<b>Estimated time:</b>	1.00 hour
<b>Target version:</b>			
<b>Description</b>			
Every participant has one scope, make this clear.  - Maintain scope ONLY in Participant. - Remove uri from Listener			
<b>Related issues:</b>			
Related to Robotics Service Bus - Tasks # 259: Create Scope class		Resolved	04/27/2011

Associated revisions

Revision 5411bc3d - 04/29/2011 12:31 PM - J. Wienke

remove duplicated scope from listener and informer and move it to participant

fixes #256

History

#1 - 04/29/2011 12:20 PM - J. Wienke

- Status changed from New to In Progress

#2 - 04/29/2011 12:31 PM - J. Wienke

- % Done changed from 0 to 100

#3 - 04/29/2011 01:10 PM - J. Wienke

- Status changed from In Progress to Resolved

- Assignee changed from S. Wrede to J. Wienke