

Robotics Service Bus - Feature #2570

Feature # 2555 (In Progress): Allow easy debugging of RSB configuration

Allow easy debugging of RSB configuration [Java]

06/17/2016 01:34 PM - J. Moringen

Status:	Resolved	Start date:	06/17/2016
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	Java	Estimated time:	0.00 hour
Target version:	rsb-0.15		
Description			

Associated revisions

Revision ffa60e08 - 09/23/2016 06:34 PM - J. Moringen

Configuration debugging in rsb-java/src/main/java/rsb/util/ConfigLoader.java

fixes #2570

- rsb-java/src/main/java/rsb/util/ConfigLoader.java
 - (ConfigLoader::CONFIG_DEBUG_VARIABLE): new constant; name of environment variable that enables configuration debugging
 - (ConfigLoader::DEBUG_INDENT_1): new constant; needed to shut up PMD
 - (ConfigLoader::DEBUG_INDENT_2): likewise
 - (ConfigLoader.debug): new member; controls configuration debugging
 - (ConfigLoader.ConfigLoader): set debug based on value of environment variable named by CONFIG_DEBUG_VARIABLE
 - (ConfigLoader.load): added debug output
 - (ConfigLoader.loadFiles): likewise
 - (ConfigLoader.loadFileIfAvailable): likewise
 - (ConfigLoader.loadEnv): likewise
- rsb-java/src/test/java/rsb/Utilities.java
 - (Utilities.createParticipantConfig): adapted to changed interface

History

#1 - 09/23/2016 02:57 PM - J. Moringen

- Status changed from New to In Progress
- Assignee set to J. Moringen

#2 - 09/23/2016 07:20 PM - J. Moringen

- Status changed from In Progress to Resolved
- % Done changed from 0 to 100

Applied in changeset commit:rsb-java|ffa60e08c53aa8b7874927421233dcefd7a28e8f.