Robotics Systems Types - Feature #2573
new rst proto files JointJerks and Weights

06/21/2016 10:59 AM - N. Dehio

Status:	Resolved		**Start date:**	06/21/2016
Priority:	Normal		**Due date:**	
Assignee:	D. Wigand		**% Done:**	100%
Category:	Type Proposal		**Estimated time:**	0.00 hour
Target version:				

Description

Please commit my new (tested) rst proto files JointJerks and Weights.
Attached you can find my git patch.

History

#1 - 06/21/2016 11:00 AM - N. Dehio

- *File 0001-added-new-proto-type-JointJerks-and-Weights.patch added*

here is the attached file...

#2 - 06/21/2016 11:02 AM - J. Wienke

- *Category set to Type Proposal*

For the weights type a unit and the indication for ordering is missing in the documentation/annotations.

#3 - 06/21/2016 12:13 PM - N. Dehio

- *File 0002-updated-annotation-documentation-of-types-JointJerks.patch added*

Attached you can find my git patch with the changes in annotation/documentation.

#4 - 06/21/2016 12:34 PM - D. Wigand

- *Status changed from New to Resolved*
- *% Done changed from 0 to 100*

Files

0001-added-new-proto-type-JointJerks-and-Weights.patch	1.75 KB	06/21/2016		N. Dehio
0002-updated-annotation-documentation-of-types-JointJerks.patch	1.36 KB	06/21/2016		N. Dehio