

Robotics Service Bus - Tasks #258

Tasks # 240 (Resolved): Refactor C++ Implementation to 2011-04-13 Domain Model

Integrate Service idea

04/27/2011 05:15 PM - J. Wienke

Status:	Resolved	Start date:	04/27/2011
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	C++	Estimated time:	4.00 hours
Target version:			
Description			
<ul style="list-style-type: none">- Create Service interface (in rsb namespace)<ul style="list-style-type: none">- Add getScope method- Add a methods to add and remove participants- Add methods to add and remove sub-services- Add methods to access participants- Add methods to access sub-services- Create Service implementation LocalService with default implementations of methods<ul style="list-style-type: none">- Services only allow sub-services and participants with more narrow scope- Create method in rsb::Factory to instantiate LocalServices			

Associated revisions

Revision 58a5e5fa - 04/30/2011 01:06 PM - J. Wienke

Add a stupid local implementation of service.

refs #258

Revision 107d707d - 04/30/2011 01:21 PM - J. Wienke

Create services in rsb::Factory

fixes #258

History

#1 - 04/30/2011 12:57 AM - J. Wienke

- Status changed from New to In Progress
- Assignee changed from S. Wrede to J. Wienke

#2 - 04/30/2011 01:07 PM - J. Wienke

Missing revision association: r707

#3 - 04/30/2011 01:22 PM - J. Wienke

- Status changed from In Progress to Resolved
- % Done changed from 0 to 100

Applied in changeset r712.