

RSB Depth Sensor Support - Feature #2629

Allow TypedStreams to generate a `std::map<std::string, std::string>` containing Meta-Data

07/26/2016 08:00 PM - M. Goerlich

Status:	New	Start date:	07/26/2016
Priority:	Normal	Due date:	
Assignee:		% Done:	0%
Category:		Estimated time:	0.00 hour
Target version:			
Description			
This would allow to publish information like frame numbers and device time of the grabbed data easing later synchronization.			