Robotics Service Bus - Feature #2648
Setters for TimesyncStrategy options

08/18/2016 01:17 PM - M. Goerlich

Status:	New		**Start date:**	08/18/2016
Priority:	Low		**Due date:**	
Assignee:			**% Done:**	0%
Category:	Timesync		**Estimated time:**	0.00 hour
Target version:				

Description

Currently the strategies can only be configured through boost::po::variables_map s. Filling those by hand is clumsy, direct setters for time frames and buffer sizes at the time frame strategy as well as for the queue size for the approx time strategy would make usage of timesync as library a lot easier.

History

#1 - 08/18/2016 01:22 PM - J. Wienke

It's probably a matter of extracting the command line handling into separate objects per strategy. Unfortunately, I don't have time atm to do this. I'd be happy about a patch ;-)

#2 - 12/12/2018 03:10 PM - J. Wienke

- Assignee deleted (J. Wienke)