Robotics Service Bus - Bug #265 Fix/Implement/Test InProcess Connectors

04/29/2011 02:47 PM - J. Moringen

Status:	Resolved	Start date:	04/29/2011	
Priority:	High	Due date:		
Assignee:	J. Moringen	% Done:	100%	
Category:	C++	Estimated time:	5.00 hours	
Target version:				
Description		·		
The InProcess co	nnector has to be disabled to implen	nent #255. In addition the following	aspects are missing	
- Unit tests				
 Event deliver 	y according to scope hierarchy			
Related issues:				
Follows Robotics Service Bus - Tasks # 255: Separate In and OutConnectors			Resolved 04/23/2011	
A				
Associated revis				
Initial rewrite of in-p	7 - 04/30/2011 12:59 AM - J. Moringen			
refs #265				
 src/CMakeLists 	s tyt: added			
	ort/inprocess/{Bus,InConnector,OutConn	ector} {h con}		
	rt/inprocess/Bus.{h,cpp}: new; a "bus" that			
across one pr				
	rt/inprocess/InConnector.{h,cpp}: new; in	connector		
-	communication			
-	rt/inprocess/OutConnector.{h,cpp}: new;	out connector		
-	communication			
-	rt/inprocess/InProcessConnector.{h,cpp}:	removed		
Revision 65610f0c	- 04/30/2011 06:04 PM - J. Moringen			
Added unit test for i	nprocess connector			
fixes #265				
- test/CMakeList	s.txt: added files test/rsbtest_inprocess.c	op and		
test/rsb/transp	oort/inprocess/InProcessConnectorTest.c	pp; added unit		
test executabl	e rsbtest_inprocess			
 test/rsbtest_inp 	process.cpp: entry point for inprocess con	nector unit		
test				
	ort/inprocess/InProcessConnectorTest.cp	p: unit test		

History

#1 - 04/29/2011 08:13 PM - J. Moringen

- Assignee set to J. Moringen

#2 - 04/29/2011 11:16 PM - J. Moringen

- Status changed from New to In Progress

- % Done changed from 0 to 50

#3 - 04/30/2011 07:09 PM - J. Moringen

- Status changed from In Progress to Resolved

- % Done changed from 50 to 100

Applied in changeset r724.