

Robotics Service Bus - Tasks #267

Tasks # 263 (Resolved): Implement coherent dynamic behavior

Fix (re)configuration of filters and handlers

04/29/2011 04:11 PM - J. Moringen

Status:	Resolved	Start date:	04/29/2011
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	C++	Estimated time:	6.00 hours
Target version:			
Description			
<ul style="list-style-type: none">- Remove (currently unused) FilterObservable- Add add/removeFilter methods- Add add/removeHandler methods<ul style="list-style-type: none">- Including "wait" flag for synchronized operation- Make sure that the EventReceivingStrategy can meet the new guarantees			

Associated revisions

Revision 599714f7 - 05/02/2011 03:35 PM - J. Wienke

remove unused FilterObservable interface

refs #267

Revision 4e81f276 - 05/02/2011 05:37 PM - J. Wienke

- remove Subscription class fixes #257
- restructure handling of Handlers and filters according to UML model without FilterObservable interface etc. refs #267

Revision 72f5b882 - 05/02/2011 06:34 PM - J. Wienke

replace filter notification for joining groups with a dedicated setScope function

refs #267

Revision 767ead25 - 05/03/2011 01:37 PM - J. Wienke

Ensure handler registration guarantees if requested, fixes #267

History

#1 - 04/29/2011 04:14 PM - J. Moringen

- Subject changed from (to Fix (re)configuration of filters and handlers
- Category set to C++
- Estimated time set to 6.00
- Parent task set to #263

#2 - 05/02/2011 03:28 PM - J. Wienke

- Status changed from New to In Progress
- Assignee set to J. Wienke

#3 - 05/03/2011 01:37 PM - J. Wienke

- Status changed from In Progress to Resolved
- % Done changed from 0 to 100

Applied in changeset r782.