Robotics Service Bus - Tasks #270
Unify semantics of activate and setScope calls for Inconnectors
05/02/2011 06:34 PM - J. Wienke

Status:	Resolved		**Start date:**	05/02/2011
Priority:	Normal		**Due date:**	
Assignee:	J. Wienke		**% Done:**	100%
Category:	C++		**Estimated time:**	0.60 hour
Target version:				

Description

The spread connector requires setScope after activate, the InProcess connector probably before. Handle this in a unified way.

Associated revisions

Revision 5505686a - 05/13/2011 07:29 PM - J. Wienke

Transform the SpreadConnectorTest into a general ConnectorTest that is now used for both connector types. Therefore unify semantics of activate call orders across connectors.

fixes #270 #271

History

#1 - 05/13/2011 07:22 PM - J. Wienke
- *Status changed from New to In Progress*
- *Assignee set to J. Wienke*

#2 - 05/13/2011 07:30 PM - J. Wienke
- *Status changed from In Progress to Resolved*
- *% Done changed from 0 to 100*

Applied in changeset r837.