

Robotics Service Bus - Enhancement #283

Unify exception handling

05/11/2011 05:29 PM - J. Wienke

Status: In Progress	Start date: 05/11/2011
Priority: Normal	Due date:
Assignee:	% Done: 30%
Category: C++	Estimated time: 2.50 hours
Target version:	
Description	
Currently there is a mixture of using a common RSB Exception base class and using std exceptions if possible. We should decide on one strategy and refactor the existing code base.	
Related issues:	
Related to Robotics Service Bus - Tasks # 1768: Evaluate Boost.Exception for ...	New 02/14/2014

History

#1 - 05/16/2011 01:41 PM - J. Wienke

[[CodingGuidelines]]

#2 - 05/16/2011 04:54 PM - J. Moringen

- Status changed from New to In Progress

- % Done changed from 0 to 30

Specification is at [[CodingGuidelines]]. Implementation remains.

#3 - 11/18/2011 03:05 PM - S. Wrede

- Target version set to 0.6

#4 - 02/27/2012 03:29 PM - J. Wienke

- Target version deleted (0.6)