

Robotics Service Bus - Tasks #292

Fix communication with C++ baseline

05/12/2011 03:11 PM - J. Wienke

Status:	Resolved	Start date:	02/17/2011
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	Python	Estimated time:	7.00 hours
Target version:	0.2		
Description			
<ul style="list-style-type: none">- md5 sums for group names- Scope class- hierarchical sending- separation of domain and wire schema- QoS- Configuration compatible to C++ implementation (currently especially spread options)			
Subtasks:			
Feature # 195: Integrate Option File Parsing			Resolved
Enhancement # 302: Adapt converter selection			Resolved
Bug # 307: QoS options are not respected by connectors			Resolved

Associated revisions

Revision 857dd494 - 05/16/2011 07:13 PM - J. Wienke

use md5 encoded group names in spread port

refs #292

Revision 915f2a70 - 05/16/2011 11:52 PM - J. Wienke

finalize scope class

refs #292

Revision 81591d81 - 05/17/2011 12:28 AM - J. Wienke

Use scope class instead of string uris

refs #292

Revision bfdd81c2 - 05/17/2011 12:23 PM - J. Wienke

implement hierarchical sending in spread

refs #292

Revision 8e559700 - 05/17/2011 02:32 PM - J. Wienke

implemented message sequencing

refs #292

Revision 564b45d0 - 05/17/2011 06:34 PM - J. Wienke

add a QoS class

refs #292

Revision f0e28b79 - 05/18/2011 11:35 AM - J. Wienke

integrate QoS

refs #292

History

#1 - 05/16/2011 02:33 PM - J. Wienke

- *Target version set to 0.2*

#2 - 05/16/2011 06:54 PM - J. Wienke

- *Status changed from New to In Progress*

#3 - 05/20/2011 03:46 PM - J. Wienke

The QoS class must still be used from ParticipantConfig.

#4 - 05/23/2011 05:39 PM - J. Moringen

- *Status changed from In Progress to Resolved*