

Robotics Service Bus - Enhancement #298

Adapt configuration mechanism for unified files across languages

05/16/2011 02:07 PM - J. Wienke

Status:	Resolved	Start date:	05/16/2011
Priority:	Urgent	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	C++	Estimated time:	1.00 hour
Target version:	0.2		
Description			
- Remove types from file, always string parameter			
Related issues:			
Blocks Robotics Service Bus - Tasks # 196: Test for consistent option file pa...		Resolved	02/17/2011

Associated revisions

Revision e6347c24 - 05/16/2011 04:30 PM - J. Moringen

Removed type information/parsing from configuration files

fixes #298

- examples/rsb.conf: removed type information from option values
- src/rsb/ParticipantConfig.cpp: do not use parseTypedValue; use getAs instead of get for non-string values
- src/rsb/transport/spread/InConnector.cpp: use getAs instead of get for non-string values
- src/rsb/transport/spread/OutConnector.cpp: likewise
- test/rsb.conf-for-smoke-test: removed type information from option values
- test/rsb/ParticipantConfigTest.cpp: store spread port as string option
- test/rsb/UserLevelTest.cpp: likewise

History

#1 - 05/16/2011 02:33 PM - J. Wienke

- Target version set to 0.2

#2 - 05/16/2011 03:05 PM - J. Moringen

- Status changed from New to In Progress

#3 - 05/16/2011 04:30 PM - J. Moringen

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

Applied in changeset r843.