

## Robotics Service Bus - Bug #306

Tasks # 291 (Resolved): Fix communication with C++ baseline

### Apply QoS from config to ports

05/20/2011 03:47 PM - J. Wienke

<b>Status:</b>	Resolved	<b>Start date:</b>	05/20/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	S. Wrede	<b>% Done:</b>	100%
<b>Category:</b>	Java	<b>Estimated time:</b>	1.50 hour
<b>Target version:</b>	0.2		
<b>Description</b>			
Neither config nor port usage is currently implemented.			

#### Associated revisions

Revision 2114f113 - 05/25/2011 01:16 PM - J. Wienke

apply QoS from properties in a hacky version until there is a participant config

fixes #306

#### History

#1 - 05/25/2011 01:16 PM - J. Wienke

- Status changed from New to Resolved

- % Done changed from 0 to 100

Applied in changeset r1194.