Robotics Service Bus - Bug #307

Tasks # 292 (Resolved): Fix communication with C++ baseline

QoS options are not respected by connectors

05/20/2011 05:23 PM - J. Moringen

Status:	Resolved	**Start date:**	05/20/2011
Priority:	Normal	**Due date:**	
Assignee:	J. Moringen	**% Done:**	100%
Category:	Python	**Estimated time:**	1.00 hour
Target version:	0.2		

Description

Associated revisions

Revision 66a57b36 - 05/23/2011 05:34 PM - J. Moringen

Pass QoS settings to created ports in rsb/__init__.py

fixes #307

- rsb/__init__.py: pass QoS settings to created Port objects in
  Subscriber and Publisher constructors

History

#1 - 05/20/2011 05:23 PM - J. Moringen

- *Category set to Python*

#2 - 05/23/2011 05:34 PM - J. Moringen

- *Assignee set to J. Moringen*

#3 - 05/23/2011 05:34 PM - J. Moringen

- *Status changed from New to Resolved*

- *% Done changed from 0 to 100*

Applied in changeset r1116.