

## Robotics Service Bus - Bug #319

### Errors mentioned in make-{informer,listener,reader} are not signaled

05/25/2011 04:29 PM - J. Moringen

<b>Status:</b>	Resolved	<b>Start date:</b>	05/25/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Moringen	<b>% Done:</b>	100%
<b>Category:</b>	Common Lisp	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>			
<b>Description</b>			
The documentation strings claim that errors {informer,listener,reader}-creation-failed would be signaled, but that is not true.			

#### Associated revisions

##### Revision 540856b6 - 05/31/2011 09:46 AM - J. Moringen

Added new conditions for failed participation in src/conditions.lisp  
refs #319

- src/conditions.lisp (listener-creation-failed): new condition; signaled when the creation of a listener fails  
(reader-creation-failed): new condition; signaled when the creation of a reader fails  
(informer-creation-failed): changed superclass rsb-error -> participation-failed
- src/package.lisp (package rsb): added exported symbols participation-failed-transport, listener-creation-failed and reader-creation-failed

##### Revision f6222386 - 08/24/2011 12:38 AM - J. Moringen

Translate errors in src/{reader,listener,informer}.lisp  
fixes #319

- src/reader.lisp (make-reader): wrap signaled errors in an `reader-creation-failed'
- src/listener.lisp (make-listener): similar for `listener-creation-failed'
- src/informer.lisp (make-informer t t): similar for `informer-creation-failed'

#### History

##### #1 - 08/24/2011 12:38 AM - J. Moringen

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset r2432.