

Robot Control Interface - Tasks #323

Handle concurrent access of ommand and status in ResourceNode

05/26/2011 11:57 AM - Anonymous

Status:	Resolved	Start date:	05/26/2011
Priority:	High	Due date:	
Assignee:		% Done:	100%
Category:		Estimated time:	2.00 hours
Target version:			
Description			
Handle concurrent access of command and status in ResourceNode (e.g. lastPositionCommand and lastPositionValue). Concurrent access by			
<ul style="list-style-type: none">- data-flow (writing command, reading status)- and synchronization with robot/simulator (reading command, writing status)			

History

#1 - 02/24/2012 06:11 PM - Anonymous

- Status changed from *New* to *Feedback*
- % Done changed from 0 to 10

Command and status variables in one setup now protected through mutexes for testing.

#2 - 03/23/2012 03:57 PM - Anonymous

- Status changed from *Feedback* to *Resolved*
- % Done changed from 10 to 100