

## Robotics Service Bus - Tasks #332

### Adapt Publisher, Subscriber and Subscription to new Concepts and Names

05/27/2011 12:33 AM - J. Moringen

<b>Status:</b>	Resolved	<b>Start date:</b>	05/26/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Wienke	<b>% Done:</b>	100%
<b>Category:</b>	Python	<b>Estimated time:</b>	2.00 hours
<b>Target version:</b>	0.3		
<b>Description</b>			

#### Associated revisions

Revision 60c2b75e - 05/27/2011 01:00 PM - J. Wienke

adapt Event interface

refs #332

#### History

**#1 - 05/27/2011 12:34 AM - J. Moringen**

- Status changed from Resolved to New
- % Done changed from 100 to 0

**#2 - 05/27/2011 12:06 PM - J. Wienke**

- Status changed from New to In Progress

**#3 - 05/27/2011 02:55 PM - J. Wienke**

- Status changed from In Progress to Resolved
- % Done changed from 0 to 100

I think most of this is done now on the pure user level.