

Robotics Service Bus - Tasks #333

Implement Local Transport

05/27/2011 12:35 AM - J. Moringen

Status:	Resolved	Start date:	05/26/2011
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	Python	Estimated time:	0.00 hour
Target version:	0.6		
Description			
Related issues:			
Blocked by Robotics Service Bus - Feature # 727: Implement Connector Subsystem		Resolved	11/18/2011

Associated revisions

Revision 02f0d482 - 01/19/2012 02:54 PM - J. Wienke

- created module and test for local transport
- implemented bus class, connectors missing

refs #333

Revision 3f15fe17 - 01/19/2012 06:45 PM - J. Wienke

Provide an OutConnector

refs #333

Revision d19443e4 - 01/19/2012 07:07 PM - J. Wienke

Add a basic InConnector

refs #333

Revision 63e191c8 - 01/20/2012 11:32 AM - J. Wienke

- Refactored the spread test so that a generic transport test is available now
- Applied generic transport test to local transport
- Fixed some waiting logic in the transport test so that the unit tests are much faster now

fixes #333

History

#1 - 05/27/2011 12:36 AM - J. Moringen

- Subject changed from Implement Local Transports to Implement Local Transport

#2 - 09/12/2011 05:06 PM - J. Wienke

- Assignee deleted (J. Wienke)

#3 - 11/18/2011 02:47 PM - S. Wrede

- *Target version changed from rsb-0.9 to 0.6*

#4 - 01/19/2012 09:18 AM - J. Wienke

- *Status changed from New to In Progress*

- *Assignee set to J. Wienke*

#5 - 01/20/2012 11:40 AM - J. Wienke

- *Status changed from In Progress to Resolved*

- *% Done changed from 0 to 100*

Applied in changeset r3259.