

Robotics Service Bus - Tasks #342

Create Factory comparable to c++ to simplify creation of participants

05/31/2011 01:30 PM - J. Wienke

Status:	Resolved	Start date:	05/31/2011
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	Python	Estimated time:	3.00 hours
Target version:	0.3		
Description			

Associated revisions

Revision f6c7a331 - 06/01/2011 12:56 PM - J. Moringen

Added interface for participant creation in rsb/__init__.py

refs #342

- rsb/__init__.py: added createListener, createInformer, etc. functions to provide a factory-like simplified interface for participant creation

Revision bac5eb46 - 06/07/2011 03:42 PM - J. Moringen

Added minimalistic test for factory in test/coretest.py

fixes #342

- test/coretest.py: added test for factory that pokes the default config; creates a listener and an informer

History

#1 - 06/01/2011 11:43 AM - J. Moringen

- Assignee changed from J. Wienke to J. Moringen

#2 - 06/05/2011 12:49 PM - J. Moringen

- Status changed from New to In Progress

- % Done changed from 0 to 50

#3 - 06/07/2011 03:49 PM - J. Moringen

- Status changed from In Progress to Resolved

- % Done changed from 50 to 100

Applied in changeset r1429.