

Robotics Service Bus - Tasks #358

dstat-like output for rsb-logger

06/09/2011 06:52 PM - J. Moringen

Status:	Resolved	Start date:	06/09/2011
Priority:	Normal	Due date:	
Assignee:		% Done:	100%
Category:		Estimated time:	0.00 hour
Target version:			
Description			

Associated revisions

Revision 9c8f3f0b - 06/09/2011 10:43 PM - J. Moringen

Added an EventFormatter that outputs statistical information

fixes #358

- logger/EventFormatter.cpp: register StatisticsEventFormatter in factory
- logger/StatisticsEventFormatter.{h,cpp}: new files; contain StatisticsEventFormatter class which collects and prints statistical information about received events

History

#1 - 06/09/2011 10:43 PM - J. Moringen

- *Project changed from Robotics Systems Commons to Robotics Service Bus*

#2 - 06/09/2011 10:50 PM - J. Moringen

- *Status changed from New to Resolved*
- *% Done changed from 0 to 100*

Applied in changeset r1469.