

Robotics Service Bus - Bug #365

Fixed XMLRPC port prevents multiple TCPROS clients

06/11/2011 12:30 AM - J. Moringen

Status:	Resolved	Start date:	06/11/2011
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	ROS Connector	Estimated time:	0.00 hour
Target version:			
Description			

History

#1 - 06/23/2011 11:35 PM - J. Moringen

- Status changed from New to Resolved
- % Done changed from 0 to 100

#2 - 08/07/2012 02:55 PM - J. Moringen

- Project changed from Rosetta Stone Project to Robotics Service Bus
- Category changed from ROS Backend to ROS Connector
- Assignee set to J. Moringen