

**Robotics Service Bus - Bug #365**  
**Fixed XMLRPC port prevents multiple TCPROS clients**

06/11/2011 12:30 AM - J. Moringen

<b>Status:</b>	Resolved	<b>Start date:</b>	06/11/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Moringen	<b>% Done:</b>	100%
<b>Category:</b>	ROS Connector	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>			
<b>Description</b>			

**History**

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**#1 - 06/23/2011 11:35 PM - J. Moringen**

- Status changed from New to Resolved
- % Done changed from 0 to 100

**#2 - 08/07/2012 02:55 PM - J. Moringen**

- Project changed from Rosetta Stone Project to Robotics Service Bus
- Category changed from ROS Backend to ROS Connector
- Assignee set to J. Moringen