

Robotics Service Bus - Tasks #370

Relicensing to LGPL

06/16/2011 12:19 PM - J. Wienke

Status: Resolved	Start date: 01/05/2012
Priority: Normal	Due date:
Assignee:	% Done: 100%
Category:	Estimated time: 0.00 hour
Target version: 0.6	
Description	
To externalize spread we need to relicense RSC and RSB to LGPL. In this context also apply the new headers proposed by the CITEC: https://www.cit-ec.de/getting_started/open_source with adoptions for the CoR-Lab.	
Subtasks:	
Tasks # 787: Relicense Python	Resolved
Tasks # 788: Relicense Java	Resolved
Tasks # 789: Relicense C++	Resolved
Tasks # 790: Relicense CL	Resolved
Related issues:	
Related to Robotics Service Bus - Feature # 725: Disable Spread by Default	Resolved 11/18/2011

History

#1 - 11/18/2011 02:47 PM - S. Wrede

- Target version changed from rsb-0.9 to 0.6

#2 - 01/05/2012 09:23 AM - J. Wienke

- Status changed from New to In Progress

#3 - 01/06/2012 12:43 PM - J. Wienke

- Status changed from In Progress to Resolved