

Robotics Service Bus - Tasks #385

Write a Inter-Transport Communication Tutorial

06/23/2011 12:27 AM - J. Moringen

Status:	Resolved	Start date:	06/23/2011
Priority:	Normal	Due date:	06/30/2011
Assignee:	J. Moringen	% Done:	100%
Category:	Documentation	Estimated time:	0.00 hour
Target version:			
Description			
Wiki page is [[Inter-Transport Communication here]].			

Associated revisions

Revision 20594797 - 06/23/2011 12:50 AM - J. Moringen

Added inter-transport communication example

refs #385

- examples/CMakeLists.txt: added files
examples/inter_transport/inprocessAndSpread.cpp and
examples/inter_transport/spreadOnly.cpp
- examples/inter_transport/inprocessAndSpread.cpp: new file;
demonstrate informer and listener with multiple connectors
- examples/inter_transport/spreadOnly.cpp: new file; only useful in
conjunction with inprocessAndSpread.cpp

Revision 67b7bd48 - 06/23/2011 01:18 AM - J. Moringen

Added a missing setter method in src/rsb/ParticipantConfig.cpp

refs #385

- src/rsb/ParticipantConfig.{h,cpp}: added missing method
ParticipantConfig::Transport::setEnabled

History

#1 - 06/23/2011 12:27 AM - J. Moringen

- Description updated

#2 - 06/23/2011 01:47 AM - J. Moringen

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

#3 - 06/23/2011 10:48 AM - S. Wrede

Sehr cool! Thx!