

Robotics Service Bus - Feature #39

High-Level Pattern: Publish-Subscribe

08/18/2010 01:29 AM - S. Wrede

Status:	Resolved	Start date:	08/18/2010
Priority:	Normal	Due date:	
Assignee:	S. Wrede	% Done:	100%
Category:	C++	Estimated time:	3.00 hours
Target version:			
Description			
Implementation based on Router should now be relatively easy. Should be tested extensively with InProcessPort as well.			

History

#1 - 08/18/2010 09:59 AM - J. Wienke

- Category set to C++

#2 - 08/23/2010 07:19 PM - S. Wrede

- Status changed from New to In Progress
- Assignee set to S. Wrede
- % Done changed from 0 to 20
- Estimated time set to 3.00

Started implementation... Nothing checked in yet...

#3 - 08/23/2010 11:23 PM - S. Wrede

- % Done changed from 20 to 40

Initial version of Publisher implementation finished, 1200 msg's per 60ms to SpreadPort / ~25 ms to InProcessPort.

#4 - 08/23/2010 11:23 PM - S. Wrede

- File mylyn-context.zip added

#5 - 08/27/2010 01:13 PM - S. Wrede

- Status changed from In Progress to Resolved
- % Done changed from 40 to 100

#6 - 08/27/2010 01:13 PM - S. Wrede

- File mylyn-context.zip added

Files

mylyn-context.zip	4.12 KB	08/23/2010	S. Wrede
mylyn-context.zip	104 KB	08/27/2010	S. Wrede