Robotics Service Bus - Enhancement #395
Provide a default implementation of getClassName for Handlers

06/28/2011 11:00 AM - J. Wienke

Status:	Resolved		**Start date:**	06/28/2011
Priority:	Normal		**Due date:**	
Assignee:			**% Done:**	100%
Category:	C++		**Estimated time:**	0.00 hour
Target version:	0.4			

Description

Clients should not be required to implement this, as the compiler warning is not intuitive.

Associated revisions

Revision c738736d - 07/03/2011 04:14 PM - J. Moringen

Added getClassName() method in src/rsb/Handler.h

fixes #395

- src/rsb/Handler.h: added getClassName() method so clients don't have
   to write their own if this default is good enough

History

#1 - 07/03/2011 04:18 PM - J. Moringen

- Status changed from New to Resolved

- % Done changed from 0 to 100

Applied in changeset r1919.

#2 - 07/25/2011 06:13 PM - S. Wrede

- Target version changed from rsb-0.10 to 0.4