

Robotics Service Bus - Enhancement #401

Add MetaData::setUserTime Methods for additional Timestamp Types

07/03/2011 02:15 PM - J. Moringen

Status: Resolved	Start date: 07/03/2011
Priority: Low	Due date:
Assignee: J. Wienke	% Done: 100%
Category: C++	Estimated time: 0.00 hour
Target version: 0.5	
Description Ideas: <ul style="list-style-type: none">- boost::posix_time::ptime- double as suggested in #381	
Related issues: Related to Robotics Service Bus - Feature # 381: Timestamp compatibilty to RO... New 06/21/2011 Related to Robotics Service Bus - Enhancement # 396: Add an Event MetaData ex... Closed 06/28/2011	

Associated revisions

Revision 778699f1 - 09/12/2011 05:42 PM - J. Wienke

remove duplicated code for timestamp setting

refs #401

Revision e847296d - 09/12/2011 06:00 PM - J. Wienke

add methods for double-based timestamp setting in MetaData

refs #401

Revision 1c22b016 - 09/12/2011 06:42 PM - J. Wienke

add conversion from ptime

fixes #401

History

#1 - 07/25/2011 06:10 PM - S. Wrede

- Target version changed from rsb-0.10 to 0.4

#2 - 07/25/2011 06:11 PM - S. Wrede

- Priority changed from Normal to Low

#3 - 08/09/2011 10:15 AM - J. Moringen

- Target version changed from 0.4 to rsb-0.10

#4 - 09/12/2011 05:36 PM - J. Wienke

- Status changed from New to In Progress

#5 - 09/12/2011 05:36 PM - J. Wienke

- Assignee set to J. Wienke

#6 - 09/12/2011 06:42 PM - J. Wienke

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

Applied in changeset r2572.

#7 - 10/27/2011 08:16 PM - J. Moringen

- Target version changed from rsb-0.10 to 0.5