

Robotics Service Bus - Feature #436

Make Reply Timeout in Client-Server Communication configurable

07/21/2011 07:36 PM - J. Moringen

Status:	Resolved	Start date:	07/21/2011
Priority:	High	Due date:	
Assignee:		% Done:	100%
Category:	C++	Estimated time:	0.00 hour
Target version:	0.4		
Description			

Associated revisions

Revision e00467e1 - 07/21/2011 09:03 PM - J. Moringen

Made reply timeout configurable in src/rsb/patterns/RemoteServer.{h,cpp}

fixes #436

- src/rsb/Factory.{h,cpp}: added maxReplyWaitTime parameter to Factory::createRemoteServer
- src/rsb/patterns/RemoteServer.{h,cpp}: added maxWaitTime parameter to WaitingEventHandler constructor; added maxReplyWaitTime to RemoteServer constructor

History

#1 - 07/21/2011 09:03 PM - J. Moringen

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset r2120.

#2 - 07/25/2011 06:12 PM - S. Wrede

- Target version changed from rsb-0.10 to 0.4