

Robotics Service Bus - Feature #471

Support for RPC clients which do not require a running server part

08/04/2011 05:17 PM - L. Schillingmann

Status:	New	Start date:	08/04/2011
Priority:	Normal	Due date:	
Assignee:		% Done:	0%
Category:		Estimated time:	0.00 hour
Target version:	rsb-1.0		

Description

It should be simple to code a rpc client which is able to handle different states of the rpc server availability:

- reconnect if server disappears and reappears
- detect server availability
- wait for server to appear (with timeout)

History

#1 - 10/21/2011 05:09 PM - S. Wrede

- Target version set to 0.5

#2 - 10/21/2011 05:12 PM - S. Wrede

- Target version changed from 0.5 to rsb-0.7

#3 - 06/18/2012 01:42 PM - J. Moringen

- Target version changed from rsb-0.7 to rsb-0.10

#4 - 12/10/2013 11:47 PM - J. Moringen

- Target version changed from rsb-0.10 to rsb-0.11

#5 - 03/24/2014 09:31 PM - J. Moringen

- Target version changed from rsb-0.11 to rsb-0.12

#6 - 12/19/2014 07:44 PM - J. Moringen

- Blocked by deleted (Feature #228: Introspection / Nameservice Interface and Initial Tool Support)

#7 - 04/27/2015 11:14 AM - J. Wienke

- Target version changed from rsb-0.12 to rsb-0.13

#8 - 03/02/2016 08:55 AM - J. Moringen

- Target version changed from rsb-0.13 to rsb-0.14

#9 - 04/15/2016 11:30 AM - J. Moringen

- Target version changed from rsb-0.14 to rsb-0.15

#10 - 07/07/2016 10:10 AM - J. Moringen

- Target version changed from rsb-0.15 to rsb-1.0