Robotics Service Bus - Bug #472
LocalServer should wait for in-progress Calls when detaching

08/04/2011 08:11 PM - J. Moringen

Status:	Resolved		**Start date:**	08/04/2011
Priority:	Normal		**Due date:**	
Assignee:	J. Moringen		**% Done:**	100%
Category:	Common Lisp		**Estimated time:**	0.00 hour
Target version:	0.4			

Description

May be an issue in other implementations as well

Associated revisions

Revision ba916d0f - 08/05/2011 12:24 AM - J. Moringen

Changed detach order of listener,informer in src/patterns/server.lisp

(hopefully) fixes #472

- src/patterns/server.lisp (detach method1): changed detach order of
  listener and informer; this way, in the `local-method' subclass, the
  method will not accept new calls and wait for in-progress call to
  finish before shutting down the informer

Revision b511caa7 - 08/05/2011 02:44 AM - J. Moringen

Added mixin class in src/transport/sometimes-interruptible-mixin.lisp

fixes #472

- src/transport/sometimes-interruptible-mixin.lisp: new file;
  contains mixin `class sometimes-interruptible-mixin' which can be
  mixed into threaded connector class which are only sometimes
  interruptible
- src/transport/package.lisp (package rsb.transport): added exported
  symbol sometimes-interruptible-mixin and connector-interruptible?
- src/transport/spread/in-push-connector.lisp (in-push-connector):
  added superclass sometimes-interruptible-mixin
- cl-rsb.asd (system cl-rsb): added file
  src/transport/sometimes-interruptible-mixin.lisp

History

#1 - 08/05/2011 12:30 AM - J. Moringen

- Status changed from New to Resolved

- % Done changed from 0 to 100

Applied in changeset r2258.

#2 - 08/05/2011 12:50 AM - J. Moringen

- Status changed from Resolved to In Progress

- % Done changed from 100 to 20

#3 - 08/05/2011 02:50 AM - J. Moringen

- Status changed from In Progress to Resolved

- % Done changed from 20 to 100

Applied in changeset r2259.