Robotics Service Bus - Tasks #479
Implement ProtocolBufferConverter

08/05/2011 08:54 PM - J. Moringen

Status:	Resolved	**Start date:**	08/05/2011
Priority:	High	**Due date:**	
Assignee:	J. Moringen	**% Done:**	100%
Category:	Python	**Estimated time:**	0.00 hour
Target version:	0.4		

Description

Related issues:

Related to Robotics Service Bus - Tasks # 476: Document Python Usage of Proto...	**Resolved**	**08/05/2011**

History

#1 - 08/05/2011 11:43 PM - J. Moringen

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

Added in r2268.