

Robotics Service Bus - Tasks #50

Initial sending and receiving of messages with python and spread

08/19/2010 01:07 PM - J. Wienke

Status:	Resolved	Start date:	08/19/2010
Priority:	High	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	Python	Estimated time:	20.00 hours
Target version:			
Description			
Related issues:			
Blocked by Robotics Service Bus - Tasks # 93: Reimplement ordered thread pool...			Resolved 08/26/2010

Associated revisions

Revision 16a816e2 - 09/10/2010 04:39 PM - J. Wienke

Initial user-level roundtrip test with spread is now working

fixes #50

History

#1 - 08/19/2010 10:36 PM - J. Wienke

- % Done changed from 20 to 30

#2 - 08/20/2010 04:58 PM - J. Wienke

- Subject changed from Initial sending of messages with python and spread to Initial sending and receiving of messages with python and spread

#3 - 09/10/2010 08:37 PM - J. Wienke

- Status changed from In Progress to Resolved

- % Done changed from 30 to 100