

Robotics Service Bus - Enhancement #551

Language-specific configuration

09/07/2011 10:09 AM - J. Moringen

Status:	Feedback	Start date:	09/07/2011
Priority:	High	Due date:	
Assignee:		% Done:	0%
Category:	Configuration	Estimated time:	0.00 hour
Target version:	rsb-1.0		

Description

We already have things like

```
[transport.spread.converter.cpp]
```

```
bool = bool
```

```
image = IpImage
```

in the current configuration scheme.

With the introduction of more technical tunable parameters (e.g. #548, #550, #551), it seems unlikely that a single configuration file can be used to configure all language implementation simultaneously.

Two solutions come to mind:

- In addition to rsb.conf, have language-specific configuration file like rsb-cpp.conf that take precedence over the generic one
- Extend the approach mentioned above and introduce language-specific options like eventprocessing.receivingstrategy.cpp

History

#1 - 12/10/2013 11:47 PM - J. Moringen

- Target version changed from rsb-0.10 to rsb-0.11

#2 - 02/06/2014 05:30 PM - J. Moringen

- Target version changed from rsb-0.11 to rsb-0.12

#3 - 04/24/2015 05:38 PM - J. Moringen

- Target version changed from rsb-0.12 to rsb-1.0