# Robotics Service Bus - Tasks #553 Introduce EventId comparable to C++

09/07/2011 03:23 PM - J. Wienke

Status: Resolved Start date: 09/07/2011

Priority: Normal Due date:

Assignee:J. Wienke% Done:100%Category:C++Estimated time:4.00 hours

Target version: 0.5

# Description

For efficient handling of source-id + sequence number we should integrate an event-id class comparable to the java version. This class will expose a uuid if required.

This will break the API compatibility!

#### Related issues:

Blocks Robotics Service Bus - Enhancement # 498: Integrate causal vector for ...

Blocked by Robotics Systems Commons - Tasks # 555: Integrate deprecation macros

Closed 09/08/2011

Blocked by Robotics Systems Commons - Tasks # 555: Integrate deprecation macros

Resolved 09/07/2011

#### Associated revisions

#### Revision 472c52d4 - 09/07/2011 09:21 PM - J. Wienke

Introduce a dedicated EventId class in C++.

The existing getId method has been marked as deprecated but stil Iremains but with slightly changes semantics as it now can raise an exception.

fixes #553

## Revision 84e68d2c - 09/07/2011 09:21 PM - J. Wienke

Introduce a dedicated EventId class in C++.

The existing getId method has been marked as deprecated but stil Iremains but with slightly changes semantics as it now can raise an exception.

fixes #553

# History

## #1 - 09/07/2011 03:46 PM - J. Wienke

- Status changed from New to In Progress

#### #2 - 09/07/2011 09:22 PM - J. Wienke

- Status changed from In Progress to Resolved
- % Done changed from 0 to 100

Applied in changeset r2548.

## #3 - 10/27/2011 08:14 PM - J. Moringen

- Target version changed from rsb-0.10 to 0.5

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