

## Robotics Systems Commons - Bug #556

### Unintuitive error message

09/08/2011 12:26 AM - Anonymous

<b>Status:</b>	Resolved	<b>Start date:</b>	09/08/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Wienke	<b>% Done:</b>	100%
<b>Category:</b>	Logging	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	0.5		

#### Description

If two different versions of RSC are used/linked this produces an error during runtime with the error message:  
terminate called after throwing an instance of 'std::invalid\_argument'  
what(): There already is a registree with key 'ConsoleLoggingSystem'.  
Aborted

It would be helpful, if this could generate a more meaningful error message, indicating the above reason.

#### Associated revisions

**Revision a75f22f7 - 09/08/2011 11:47 AM - J. Wienke**

raise a more special warning in cases where rsc could be double-linked in different versions.

fixes #556

#### History

**#1 - 09/08/2011 12:34 AM - J. Wienke**

Hm, sounds like a very rare error case to optimize. ;) Double-linking is always something really bad and this is by accident the first thing you notice.  
Be happy that it's not much worse or unpredictable. ;)

**#2 - 09/08/2011 11:08 AM - J. Wienke**

- Status changed from *New* to *In Progress*
- Target version set to 0.5

**#3 - 09/08/2011 11:47 AM - J. Wienke**

- Status changed from *In Progress* to *Resolved*
- % Done changed from 0 to 100

Applied in changeset r352.