

Robotics Service Bus - Bug #559

Use dynamic spread library by default

09/08/2011 03:52 PM - S. Herbrechtsmeier

Status:	Resolved	Start date:	09/08/2011
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	C++	Estimated time:	0.00 hour
Target version:	rsb-0.10		

Description

Don't use static libraries by default, as it is not guaranty that they are position independent, which is required to link them into dynamic libraries. If the user wants static linking he can reactivate it by setting SPREAD_USE_STATIC to TRUE.

Associated revisions

Revision 8e1fb353 - 09/08/2011 04:16 PM - J. Wienke

make shared library for spread the default

fixes #559

History

#1 - 09/08/2011 04:12 PM - J. Wienke

- *Category set to C++*
- *Assignee set to J. Wienke*
- *Target version set to rsb-0.10*

I cannot make this the default for 0.4 as it may break build of dependent software.

#2 - 09/08/2011 04:16 PM - J. Wienke

- *Status changed from New to Resolved*
- *% Done changed from 0 to 100*

Applied in changeset r2553.