

Robotics Service Bus - Tasks #560

Enhancement # 498 (Closed): Integrate causal vector for events

Add cause checking to integration test

09/08/2011 05:45 PM - J. Wienke

Status:	Resolved	Start date:	09/08/2011
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	Language Integration	Estimated time:	2.00 hours
Target version:	0.5		
Description			

Associated revisions

Revision 8972a1bd - 10/20/2011 07:14 AM - J. Moringen

Added generation/validation of cause event ids in informers/listeners

fixes #560

- cpp/informer.cpp: add one cause event id to published events
- cpp/listener.cpp: validate scope, payload size and cause event id of received events
- java/informer.java: add one cause event id to published events
- java/listener.java: validate scope, payload size and cause event id of received events
- lisp/informer.lisp: add one cause event id to published events
- lisp/listener.lisp: validate scope, payload size and cause event id of received events
- python/informer.py: add one cause event id to published events
- python/listener.py: validate scope, payload size and cause event id of received events

History

#1 - 09/12/2011 04:16 PM - J. Wienke

- Status changed from New to Rejected

The protocol is currently very simple and adding this check to the test would be too much work right now.

#2 - 10/20/2011 02:27 AM - J. Moringen

- Status changed from Rejected to In Progress
- Assignee set to J. Moringen
- Target version changed from rsb-0.10 to 0.5
- % Done changed from 0 to 40

#3 - 10/20/2011 07:18 AM - J. Moringen

- Status changed from In Progress to Resolved
- % Done changed from 40 to 100

Applied in changeset r2912.