

Robotics Service Bus - Tasks #567

Export dependencies through cmake

09/13/2011 08:33 PM - J. Wienke

Status:	Resolved	Start date:	09/13/2011
Priority:	Normal	Due date:	
Assignee:		% Done:	100%
Category:	C++	Estimated time:	2.00 hours
Target version:	0.5		
Description			
http://www.vtk.org/Wiki/CMake/Tutorials/How_to_create_a_ProjectConfig.cmake_file			
Understand this. Downstream projects should not be responsible of searching upstream libraries.			

Associated revisions

Revision 880cdf96 - 09/14/2011 01:07 PM - J. Wienke

proivde a cmake version file

refs #567

Revision ab06cd42 - 09/14/2011 02:25 PM - J. Wienke

use cmake exports for rsb

fixes #567

Revision 17093c13 - 09/14/2011 02:34 PM - J. Wienke

correctly export all other dependencies. the hack for the static lib did not work

refs #567

Revision 3cea5ec9 - 09/14/2011 08:16 PM - J. Moringen

Avoid duplicate execution in RSBConfig.cmake.in

refs #567

- RSBConfig.cmake.in: prevent the file from being executed multiple time when included multiple times; otherwise duplicate library targets cause errors

History

#1 - 09/14/2011 01:07 PM - J. Wienke

- Status changed from New to In Progress

#2 - 09/14/2011 02:26 PM - J. Wienke

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

Applied in changeset r2602.

#3 - 09/14/2011 02:29 PM - J. Wienke

Stefan, can you check that this now suites or discussions on the mailing list about exporting dependencies etc.?

#4 - 10/27/2011 08:30 PM - J. Moringen

- *Target version changed from rsb-0.10 to 0.5*