

Robotics Service Bus - Feature #606

Deliver a double converter by default

10/04/2011 03:11 PM - Anonymous

<b>Status:</b>	Rejected	<b>Start date:</b>	10/04/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>		<b>% Done:</b>	0%
<b>Category:</b>	C++	<b>Estimated time:</b>	1.00 hour
<b>Target version:</b>			
<b>Description</b>			
<p>We should deliver a double converter by default, like we already do for string, bool, uint64, etc.</p> <p>Double is probably the most used type in robotics, so this would come quite handy for new users to quickly test RSB for exchanging values.</p>			

History

#1 - 10/04/2011 03:32 PM - J. Moringen

- Status changed from New to Feedback

Duplicate of #484. The complaint is valid, though.

#2 - 10/04/2011 03:33 PM - J. Moringen

- Status changed from Feedback to Rejected