

Robotics Service Bus - Feature #606

Deliver a double converter by default

10/04/2011 03:11 PM - Anonymous

Status:	Rejected	Start date:	10/04/2011
Priority:	Normal	Due date:	
Assignee:		% Done:	0%
Category:	C++	Estimated time:	1.00 hour
Target version:			
Description			
<p>We should deliver a double converter by default, like we already do for string, bool, uint64, etc. Double is probably the most used type in robotics, so this would come quite handy for new users to quickly test RSB for exchanging values.</p>			

History

#1 - 10/04/2011 03:32 PM - J. Moringen

- Status changed from *New* to *Feedback*

Duplicate of #484. The complaint is valid, though.

#2 - 10/04/2011 03:33 PM - J. Moringen

- Status changed from *Feedback* to *Rejected*