

## Robotics Service Bus - Tasks #625

### Improve performance of Python implementation

10/13/2011 10:15 PM - S. Wrede

<b>Status:</b>	Resolved	<b>Start date:</b>	10/13/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Wienke	<b>% Done:</b>	100%
<b>Category:</b>	Python	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	0.5		
<b>Description</b>			
- Removal of Logging Overhead: see r2830			

#### History

---

##### #1 - 10/14/2011 05:26 PM - J. Wienke

What is the aim of this issue?

##### #2 - 10/14/2011 07:49 PM - S. Wrede

- Priority changed from Urgent to Normal

To further trace this (and for the records when we do the 0.5 release)...

##### #3 - 10/20/2011 01:05 AM - J. Moringen

- Tracker changed from Bug to Tasks

- Subject changed from Python Performance Improvements to Improve performance of Python implementation

##### #4 - 10/20/2011 03:53 PM - J. Wienke

- Status changed from Feedback to Resolved

- % Done changed from 90 to 100

We cannot find more use in this ticket being open. If there are further improvements required, please open a new issue. Otherwise this issue will never be closed. ;)