

Robotics Service Bus - Feature #633

Implement not-origin filter

10/14/2011 11:01 PM - J. Moringen

Status:	Resolved	Start date:	10/14/2011
Priority:	Normal	Due date:	
Assignee:		% Done:	100%
Category:	C++	Estimated time:	0.00 hour
Target version:			
Description			
Useful for avoiding self-notifications.			

Associated revisions

Revision 9f735dc4 - 10/15/2011 06:53 PM - J. Moringen

Added OriginFilter class in src/rsb/filter/OriginFilter.{h,cpp}

fixes #633

- src/rsb/filter/OriginFilter.{h,cpp}: new files; interface and implementation of OriginFilter class
- src/CMakeLists.txt: added files src/rsb/filter/OriginFilter.{h,cpp}

History

#1 - 10/15/2011 07:00 PM - J. Moringen

- Status changed from *New* to *Resolved*
- % Done changed from 0 to 100

Applied in changeset r2842.